Abstract

In this research work, we focus on development of a numerical algorithm which is well suited as integrator of initial value problems of order two. Exponential function is fitted into the Chebyshev polynomials for the formulation of this new numerical integrator. The efficiency, ingenuity and computational reliability of any numerical integrator are determined by investigating the zero stability, consistency and convergence of the integrator. Findings reveal that this algorithm is convergent. On comparison, the solutions obtained through the algorithm compare favourably well with the analytical solutions.

Keywords: Chebyshev polynomial, Convergence, IVPs, Numerical Integrator, ODEs

1. Introduction

The search for numerical methods to accurately integrate ordinary differential equation is on the increase and of recent, much effort has been concentrated on solving initial and boundary value problems. Variety of tools (polynomials) have been employed to develop numerical methods for integrating mathematical problems and modelling, an important perspective which cuts across all kind of mathematical problems.

Butcher [1], Lambert [2, 3] and Henrici [4] discussed extensively the approach of reducing higher order ODEs to a system of lower order, specifically, order one and then applying various methods available for solving the resulting system of rst order IVPs. The increase in the number of equations resulting from this approach has been reported as its major setback (see [5, 6]). Jator and Li [7] formulated block methods which directly solve higher order ordinary differential equations without reducing the ODEs to system of first order equations. Researchers such as [8-11] modelled series of algorithms which on their implementation, solve first order initial value problems. Enoch and Ibijola [12] developed a self-adjusting numerical integrator with an inbuilt switch for discontinuous initial value problems.

The aim of developing new methods has always been to introduce a new approach with a target to reduce the error of approximation and thereby improve on the accuracy and efficiency of existing methods hence, this research paper. In this paper, we consider Chebyshev polynomial owing to its elegant properties whereby exponential function shall be fitted into Chebyshev polynomials to develop a direct integrator of second order IVPs.

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2. Formulation of Exponentially fitted Chebyshev Method

This section describes the formulation of an algorithm which directly integrate second order initial value problems. We set out by considering a function of the form

\[ f(x) = a_n T_n(x) + e^x \]  \hspace{1cm} (1)

where \( T_n(x) \) is a Chebyshev polynomial of first degree, \( e^x \) is exponential function and \( a_n \) is a constant to be determined in the interval \([a, b]\), \( x_n = a + nh, n = 0, 1, 2, \ldots \) and \( h \) is the step size. We consider \( y_n \) as numerical estimate to the theoretical value \( y(x_n) \) and \( f_n \) represents \( f(x_n, y_n) \) with assumption that the theoretical solution \( y(x) \) of a given ordinary differential equation can be locally represented in the interval \([x_n, x_{n+1}]\) by the interpolating function described above. Considering \( T_n(x) \) in equation 1 for \( n = 0, 1, 2, \ldots \), we obtain

\[ f(x) = a_0 + a_1 x + a_2 (2x^2 - 1) + e^x \]  \hspace{1cm} (2)

where \( a_0, a_1 \) and \( a_2 \) are constants and also real undetermined coefficient. Interpolating equation 2 at point \( x \), we obtain, for

\[ f(x_n) = a_0 + a_1 x_n + a_2 (2x_n^2 - 1) + e^{x_n} \equiv y_n \]  \hspace{1cm} (3)

and for \( x = x_{n+1} \)

\[ f(x_{n+1}) = a_0 + a_1 (x_n + h) + a_2 (2(x_n + h)^2 - 1) + e^{x_n + h} \equiv y_{n+1} \]  \hspace{1cm} (4)

where \( x_{n+1} = x_n + h \)

Differentiating the interpolating function with respect to \( x \) and obtaining the first, second and third derivatives of the function, we have

\[ F'(x_n) = a_1 + 4a_2 x + e^x = f_n \]  \hspace{1cm} (5)

\[ F''(x_n) = 4a_2 + e^x = f''_n \]  \hspace{1cm} (6)

\[ F'''(x_n) = e^x = f'''_n \]  \hspace{1cm} (7)

Thus, equations 5, 6 and 7 become

\[ a_1 + 4a_2 x + e^x = f_n \equiv d_1 \]  \hspace{1cm} (8)

\[ 4a_2 + e^x = f''_n \equiv d_2 \]  \hspace{1cm} (9)

\[ e^x = f'''_n \equiv d_3 \]  \hspace{1cm} (10)

Subtracting equation 3 from equation 4 and simplifying yields

\[ Y = a_1 (x_n + h) + a_2 (2(x_n + h)^2 - 1) + e^{x_n + h} - a_1 x_n - a_2 (2x_n^2 - 1) - e^{x_n} \]  \hspace{1cm} (11)

where \( Y = y_{n+1} - y_n \), which gives

\[ y_{n+1} = y_n + a_1 (x_n + h) + a_2 (2(x_n + h)^2 - 1) + e^{x_n + h} \]  \hspace{1cm} (12)

Solving equations 8 and 9, the values coefficients \( a_i's \) are obtained and substituted in equation 2 to have

\[ y_{n+1} = \frac{y_n + (d_1 - (d_2 - e^x)x - e^x)(x_n + h) + \left( \frac{4}{3} d_2 - \frac{1}{3} e^x \right) \left( 2(x_n + h)^2 - 1 \right) + e^{x_n + h} \right)}{4} \]

Equation 13 is therefore the new numerical integrator for integrating second order initial value problems.

3. Analysis of the Method

The convergence of the scheme is investigated using Lipschitz Continuity theorem as discussed by Fatunla [13, 14] and Lambert [2].

Consider \( f(x, y) - f(x, y') = \frac{\partial f(x, y)}{\partial y} (x, y') \) and \( L = \sup_{(x, y) \epsilon \text{Dom}} \frac{\partial f(x, y)}{\partial y} \) where \( f(x, y) \) is defined for all points \((x, y)\) in the region \( D = \{(x, y) | x_0 \leq x \leq x_n, -\infty < y < \infty \} \), \( x_0 \) and \( x_n \) are finite and \( L \) is Lipschitz constant such that for \( L \leq 0 \),

\[ |f(x, y) - f(x, y')| \leq L |y - y'| \]  \hspace{1cm} (14)

\[ f(x, y) - f(x, y') = \frac{\partial f(x, y)}{\partial y} \]  \hspace{1cm} (15)

Equation 14 can be satisfied if we choose

\[ L = \sup \frac{\partial f(x, y)}{\partial y} \]  \hspace{1cm} (16)

From equation 13 that is, the numerical scheme developed, we have

\[ y_{n+1} = y_n + \left( d_1 - 4 \left( \frac{1}{4} d_2 - \frac{1}{4} e^x \right) x - e^x \right) (x_n + h) + \left( \frac{4}{3} d_2 - \frac{1}{3} e^x \right) \left( 2(x_n + h)^2 - 1 \right) + e^{x_n + h} \]

\[ - (d_1 - 4 \left( \frac{1}{4} d_2 - \frac{1}{4} e^x \right) x - e^x) x_n - \left( \frac{4}{3} d_2 - \frac{1}{3} e^x \right) \left( 2x_n^2 - 1 \right) - e^{x_n} \]

By Lambert [2] and Fatunla [13] as mentioned above,

\[ f(x, y) - f(x, y') = \frac{\partial f(x, y)}{\partial y} \]  \hspace{1cm} (17)

\[ L = \sup_{(x, y) \epsilon \text{Dom}} \frac{\partial f(x, y)}{\partial y} \]

By Henrici [9], \(| \phi(x, y'; h) - \phi(x, y; h) | \leq L |y - y'| \) where \( x \in (a, b), y \in (-\infty, \infty), a \leq h \leq h_o; h_o > 0 \). From equation 14,

\[ y_{n+1} = y_n + \left( d_1 - 4 \left( \frac{1}{4} d_2 - \frac{1}{4} e^x \right) x - e^x \right) (x_n + h) + \left( \frac{4}{3} d_2 - \frac{1}{3} e^x \right) \left( 2(x_n + h)^2 - 1 \right) + e^{x_n + h} \]
\[-(d_1 - 4\left(\frac{1}{4}d_2 - \frac{1}{4}e^4\right)x - e^4)x_n - \left(\frac{1}{4}d_2 - \frac{1}{4}e^4\right)(2x_n^2 - 1) - e^4\]

This is further simplified to have

\[y_{n+1} = y_n + h \left( (d_2 - e^4) x + e^4 - d_1 + \frac{1}{4} (d_2 - e^4)(2h + 4x) \right) + e^{x+h} - e^x \quad (18)\]

Recall that

\[d_1 = F(x, y) \quad (19)\]
\[d_2 = F'(x, y) \quad (20)\]

Substituting equations 19 and 20 into 18 and simplifying the resulting equation, we have

\[y_{n+1} = y_n + h \left( 2(x + \frac{h}{2}) (F' (x, y) - e^4) \right) + e^x - F (x, y)] + e^{x+h} - e^x \quad (21)\]

We write the functional dependence \(y_{n+1}\) on the quantities \(x_n\), \(y_n\) and \(h\) in the form

\[\phi(x_n, y_n; h) = \left( (F' (x, y) - e^4) (2x_n + \frac{h}{2}) - F (x, y) + e^4 \right) \quad (22)\]

\[\phi(x_n, y^*_n; h) = \left( (F' (x, y^*) - e^4) (2x_n + \frac{h}{2}) - F (x, y^*) + e^4 \right) \quad (23)\]

\[\phi(x_n, y_n; h) - \phi(x_n, y^*_n; h) = \left( (F' (x, y) - e^4) \right) \left( (2x_n + \frac{h}{2}) - F (x, y) + e^4 \right) - \left( (F' (x, y^*) - e^4) \right) \left( (2x_n + \frac{h}{2}) - F (x, y^*) + e^4 \right) \quad (24)\]

\[y_{n+1} = y_n + h\phi(x_n, y_n; h) \quad (25)\]

Applying equation 17, we have

\[F(x_n, y^*_n) - F(x_n, y_n) = \frac{\partial F(x_n, y_n)}{\partial y}(y^*_n - y_n) \quad (25)\]
\[F'(x_n, y^*_n) - F'(x_n, y_n) = \frac{\partial F'(x_n, y_n)}{\partial y}(y^*_n - y_n) \quad (26)\]

where \(L_1 = \sup_{(x,y)\in Dom} \frac{\partial F(x_n, y_n)}{\partial y}\) and
\(L_2 = \sup_{(x,y)\in Dom} \frac{\partial F'(x_n, y_n)}{\partial y}\).

Putting equations 25 and 26 into 24, we have

\[\phi(x_n, y_n; h) - \phi(x_n, y^*_n; h) = \left[ \frac{\partial F(x_n, y_n)}{\partial y} \right](y^*_n - y_n) \quad (27)\]

Putting \(L_1\) and \(L_2\) into equation 27 and letting \(P = \left( 2 + \frac{h}{2} \right)\), we obtain

\[\phi(x_n, y^*_n; h) - \phi(x_n, y_n; h) = \left[ (L_1 + PL_2) \right] (y_n - y^*_n) \quad (28)\]

If \(L_1 + PL_2 = L\), equation 28 becomes \(\phi(x_n, y^*_n; h) - \phi(x_n, y_n; h) = L(y_n - y^*_n)\) and \(\left| \phi(x_n, y^*_n; h) - \phi(x_n, y_n; h) \right| \leq L \left| y_n - y^*_n \right|\). This shows clearly that the numerical scheme is convergent as it satisfies the Lipschitz condition.

4. Numerical Experiments

Two test problems are considered here to implement the derived scheme.

**Example 1:**

\[y'' = -\frac{6}{x} y - \frac{4}{x^2} y, \quad y(1) = 1, \quad y'(1) = 1; \quad h = \frac{0.1}{32}.\]

Exact solution:

\[y(x) = \frac{5}{3x} - \frac{2}{3x^2}.\]

**Example 2:**

\[y'' = -y, \quad y(0) = 1, \quad y'(0) = 1, \quad h = 0.001.\]

Exact solution:

\[y(x) = \cos x.\]

The graphical solutions of the examples above are shown below.

![Graphical solution](image)

**Figure 1:** Comparison of the exact and numerical solutions for example 1.

4.1. Discussion of Results

We implement the constructed scheme on the two examples considered in this work. In Figures 1 and 2, we compare the
accuracy of the proposed method with the exact solution. From the graphs displayed, it is evident that the new scheme compares favourably with the exact solutions.

5. Conclusion

We have developed a scheme to solve second order Initial Value Problems in Ordinary Differential Equations (ODE) using Chebyshev polynomials with exponential function fitted into it. Formulation of numerical integrator using the generated polynomials has been demonstrated. The scheme has been implemented using two test problems. On comparison, the solutions obtained through the numerical scheme recovers the analytical solutions. We therefore recommend the technique for numerical algorithm as we hope to extend the approach to solve boundary value problems.

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References